

Extension of the Gelfond-Lifschitz Reduction for Preferred Answer Sets

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- If a slope is too difficult for a user, do not recommend it.
- If a user likes a slope, recommend it.
- If there is no snow on a slope, do not recommend it.

Recommend or not to recommend?

- the first rule is the weakest one,
- the third rule is the strongest one.

Do not recommend

$$\mathcal{P} = (P, <)$$

r_1 :	$\neg rec$	\leftarrow	<i>difficult, not rec</i>
r_2 :	rec	\leftarrow	<i>likes, not $\neg rec$</i>
r_3 :	$\neg rec$	\leftarrow	<i>no_snow, not rec</i>

$$r_1 < r_2 < r_3$$

Answer Sets

$$\{rec, \dots\}, \{\neg rec, \dots\}$$

How should semantics change in the presence of preferences on rules?

Select the subset of the standard answer sets as preferred.

Preferred Answer Sets

$\{\neg rec, \dots\}$

Existing approaches, e.g.:

- Brewka and Eiter, Delgrande et al., Wang et al.,
- Zhang and Foo, Sakama and Inoue, Šeřfránek

Independent rules: $\{a, b\}$

$r_1 : a \leftarrow$

$r_2 : b \leftarrow$

Exception: $\{b\}$

$r_1 : a \leftarrow \textit{not } b$

$r_2 : b \leftarrow$

Conflicting rules: $\{a\}, \{b\}$

$r_1 : a \leftarrow \textit{not } b$

$r_2 : b \leftarrow \textit{not } a$

Preference handling as the reverse transformation

conflicts \rightarrow exceptions?

Remove default negated literals from a preferred conflicting rule

\mathcal{P}		$t(\mathcal{P})$
$r_1 : a \leftarrow not\ b$	\rightarrow	$r_1 : a \leftarrow$
$r_2 : b \leftarrow not\ a$		$r_2 : b \leftarrow not\ a$

$r_2 < r_1$

And define $\mathcal{PAS}(\mathcal{P}) = \mathcal{AS}(t(\mathcal{P}))$

- How the transformation looks like?
- What is the direct definition of the semantics?
- What are the properties of the semantics?
- What is the connection with existing approaches?

A rule is an expression of the form

$$l_0 \leftarrow l_1, \dots, l_m, \text{not } l_{m+1}, \dots, \text{not } l_n,$$

$$\text{head}(r) = l_0, \text{body}^+(r) = \{l_1, \dots, l_m\}, \text{body}^-(r) = \{l_{m+1}, \dots, l_n\}$$

An answer set of a program P without *not* is given by the bottom-up evaluation using $T_P(X) = \{head(r) : body^+(r) \subseteq X\}$ from \emptyset .

$$\begin{array}{ll} r_1 : a \leftarrow & X_0 = \emptyset \\ r_2 : b \leftarrow a & X_1 = \{a\} \\ r_3 : d \leftarrow c & X_2 = \{a, b\} \\ & X_3 = X_2 \end{array}$$

Answer sets of programs with *not* are defined using Gelfond-Lifschitz reduction:

For a program P and a set of literals S we obtain P^S by:

- removing each rule r with $body^-(r) \cap S \neq \emptyset$, and
- removing *not* from the remaining rules.

Set of literal S is an answer set of a program P iff

S is answer set of P^S

Two rules are conflicting if they are of the form

$$a \leftarrow \dots, \textit{not } b$$
$$b \leftarrow \dots, \textit{not } a$$

Simple case – Each head has different head:

Remove from the body of a rule the head of a less preferred conflicting rule.

$$\begin{array}{lcl}
 r_1 : a \leftarrow \text{not } b & & a \leftarrow \\
 r_2 : b \leftarrow \text{not } a & \rightarrow & b \leftarrow \text{not } a
 \end{array}$$

$$r_2 < r_1$$

This is not usable in general:

$$\begin{array}{lcl} r_1 : a \leftarrow x, \text{ not } b & & a \leftarrow x \\ r_2 : b \leftarrow y, \text{ not } a & \rightarrow & b \leftarrow y \\ r_3 : a \leftarrow z, \text{ not } b & & a \leftarrow z, \text{ not } b \end{array}$$

$$r_3 < r_2 < r_1$$

In the body of r_2 we need to distinguish between "a" derived by r_1 and r_3 .

Solution:

- Introduce special-purpose literals n_r ,
- divide each rule r into rules:
 - deriving n_r ,
 - deriving $head(r)$,
- replace default negated literals by n_r literals

$$\begin{array}{lll}
 r_1 : a \leftarrow x, \text{ not } b & n_{r_1} \leftarrow x, \text{ not } n_{r_2} & n_{r_1} \leftarrow x \\
 & a \leftarrow n_{r_1} & a \leftarrow n_{r_1} \\
 r_2 : b \leftarrow y, \text{ not } a & \rightarrow n_{r_2} \leftarrow y, \text{ not } n_{r_1}, \text{ not } n_{r_3} \rightarrow & n_{r_2} \leftarrow y, \text{ not } n_{r_1} \\
 & b \leftarrow n_{r_2} & b \leftarrow n_{r_2} \\
 r_3 : a \leftarrow z, \text{ not } b & n_{r_3} \leftarrow z, \text{ not } n_{r_2} & n_{r_3} \leftarrow z, \text{ not } n_{r_2} \\
 & a \leftarrow n_{r_3} & a \leftarrow n_{r_3}
 \end{array}$$

$$r_3 < r_2 < r_1$$

An answer set S can be represented by the rules that generate it:

$$\Gamma_P(S) = \{r \in P : \text{body}^+(r) \subseteq S \text{ and } \text{body}^-(r) \cap S = \emptyset\}$$

An answer set X is preferred iff for each $r \in P \setminus \Gamma_P(X)$:

- $body^+(r) \not\subseteq X$, or
- $body^-(r) \cap \{head(t) : t \in \Gamma_P(X) \text{ and } t \text{ is not less preferred conflicting with } r\} \neq \emptyset$.

$\mathcal{P} = (P, <)$.

- Compatible with the answer set semantics:
 - $\mathcal{PAS}(\mathcal{P}) \subseteq AS(P)$,
 - If $< = \emptyset$ or P is stratified, then $\mathcal{PAS}(\mathcal{P}) = AS(P)$
- Brewka and Eiter's Principle I and II are satisfied.

- Deciding whether a $PAS(\mathcal{P}) \neq \emptyset$ is NP-complete.
- Semantics does not guarantee existence of a preferred answer set when a standard one exists:

$r_1 : a \leftarrow not\ b$

$r_2 : b \leftarrow not\ a$

$r_3 : inc \leftarrow a, not\ inc$

$r_2 < r_1$

- If P is call-consistent and head-consistent (no integrity constraints via default and explicit negation), then

$$\mathcal{PAS}(P) \neq \emptyset \text{ if } \mathcal{AS}(P) \neq \emptyset$$

Schaub and Wang: $\mathcal{PAS}_{DST}(\mathcal{P}) \subseteq \mathcal{PAS}_{WZL}(\mathcal{P}) \subseteq \mathcal{PAS}_{BE}(\mathcal{P})$

We: $\mathcal{PAS}_{BE}(\mathcal{P}) \subseteq \mathcal{PAS}(\mathcal{P})$

An answer set X of P is a *BE preferred answer set* of \mathcal{P} iff there is an enumeration $\langle r_i \rangle$ of $\Gamma_P(X)$ such that for each i, j :

- 1 if $r_i < r_j$, then $j < i$, and
- 2 if $r_i < r$ and $r \in P \setminus \Gamma_P(X)$, then
 - 1 $body^+(r) \not\subseteq X$ or
 - 2 $body^-(r) \cap \{head(r_j) : j < i\} \neq \emptyset$ or
 - 3 $head(r) \in X$

An answer set X is preferred iff for each $r \in P \setminus \Gamma_P(X)$:

- $body^+(r) \not\subseteq X$, or
- $body^-(r) \cap \{head(t) : t \in \Gamma_P(X) \text{ and } t \text{ is not less preferred conflicting with } r\} \neq \emptyset$.

- The semantics is not prescriptive
- The semantics is equivalent with answer set semantics for stratified programs
- Ignores preferences between non-conflicting rule, suitable when preferences are automatically generated.

- Restriction to direct conflicts were made for two reasons:
 - It is good to proceed from simple cases to complex ones,
 - It was necessary in order to obtain the result

$$\mathcal{PAS}_{BE}(\mathcal{P}) \subseteq \mathcal{PAS}(\mathcal{P})$$

- Plan to extend the semantics to indirect conflicts